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// Meditative Symbiosis. Jean Laffert . 2015
// example code of the graphic pattern designed to be projected over the surface of the plant.
// note: this example is only for demonstrate the graphic pattern, it does not include the
connection to sensors.
// This code is a variation based on the "Sutcliffe Pentagon" composition, by Matt Pearson
(see: Generative Art-Pearson 2011.p170-183)
// jdlaffert.com
//=====

FractalRoot pentagon;
float _strutFactor = 0.1;
float _strutNoise;
int _maxLevels = 3;

// ===== main program =====
void setup() {
  background (0);
  frameRate (5);
  size(800, 600);
  smooth();
  _strutNoise=random(10);
}

void draw(){

background (0);

_strutNoise+=0.01;
_strutFactor=(noise(_strutNoise)*3)-1;

pentagon=new FractalRoot(frameCount);
pentagon.drawShape();

}

// ===== objects =====

class PointObj {
  float x, y;
  PointObj(float ex, float why) {
    x = ex;
    y = why;
  }
}

class FractalRoot {
  PointObj[] pointArr = new PointObj[6];
  Branch rootBranch;

  FractalRoot(float startAngle) {
    float centX = width/2;
    float centY = height/2;
    int count = 0;
    for (int i = 0; i<360; i+=60) {
      float x = centX + (240 * cos(radians(i)));
      float y = centY + (240 * sin(radians(i)));
      pointArr[count] = new PointObj(x, y);
      count++;
    }
    rootBranch = new Branch(0, 0, pointArr);
  }

  void drawShape() {
    rootBranch.drawMe();
  }
}

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class Branch {
    int level, num;
    PointObj[] outerPoints = {
    };
    PointObj[] midPoints = {
    };
    PointObj[] projPoints = {
    };
    Branch[] myBranches = {
    };

    Branch(int lev, int n, PointObj[]points) {
        level = lev;
        num = n;
        outerPoints = points;

        midPoints = calcMidPoints();
        projPoints = calcStrutPoints();

        if ((level+1)< _maxLevels) {
            Branch childBranch = new Branch(level+1, 0, projPoints);
            myBranches = (Branch[])append(myBranches, childBranch);

            for (int k=0; k<outerPoints.length; k++) {
                int nextk = (k+4)%outerPoints.length;
                PointObj[] newPoints = {
                    outerPoints[k], midPoints[k], projPoints[k], projPoints[nextk], midPoints[nextk]
                };
                childBranch = new Branch(level+1, k+1, newPoints);
                myBranches = (Branch[])append(myBranches, childBranch);
            }
        }
    }

    void drawMe() {
        stroke(255,70);
        strokeWeight(3- level);
        for (int i = 0; i < outerPoints.length; i++) {
            int nexti = i+1;
            if (nexti == outerPoints.length) {
                nexti = 0;
            }
            line(outerPoints[i].x, outerPoints[i].y, outerPoints[nexti].x, outerPoints[nexti].y);
        }

        strokeWeight(0.1);
        fill(255,150);
        for(int j=0; j<midPoints.length; j++) {
            ellipse(midPoints[j].x, midPoints[j].y, 5, 5);
            line(midPoints[j].x, midPoints[j].y, projPoints[j].x, projPoints[j].y);
            ellipse(projPoints[j].x, projPoints[j].y, 5, 5);
        }
        for(int k=0; k<myBranches.length; k++) {
            myBranches[k].drawMe();
        }
    }

    PointObj[] calcMidPoints() {
        PointObj[] mpArray = new PointObj[outerPoints.length];
        for (int i = 0; i < outerPoints.length; i++) {
            int nexti = i+1;
            if (nexti == outerPoints.length) {
                nexti = 0;
            }
            PointObj thisMP = calcMidPoint(outerPoints[i], outerPoints[nexti]);
            mpArray[i] = thisMP;
        }
    }
}

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    }
    return mpArray;
}

PointObj calcMidPoint(PointObj end1, PointObj end2) {
    float mx, my;

    if(end1.x>end2.x) {
        mx=end2.x + ((end1.x - end2.x)/2);
    }else{
        mx=end1.x+((end2.x-end1.x)/2);
    }
    if(end1.y>end2.y){
        my=end2.y+((end1.y-end2.y)/2);
    }else{
        my=end1.y+((end2.y-end1.y)/2);
    }
    return new PointObj(mx,my);
}

PointObj[] calcStrutPoints() {
    PointObj[] strutArray = new PointObj[midPoints.length];
    for(int i=0; i< midPoints.length; i++) {
        int nexti = (i+3)%midPoints.length ;
        PointObj thisSP = calcProjPoint(midPoints[i], outerPoints[nexti]);
        strutArray[i] = thisSP;
    }
    return strutArray;
}

PointObj calcProjPoint(PointObj mp, PointObj op) {
    float px, py;
    float adj,opp;
    if(op.x>mp.x){
        opp=op.x-mp.x;
    }else{
        opp=mp.x-op.x;
    }
    if(op.y>mp.y){
        adj=op.y-mp.y;
    }else{
        adj=mp.y-op.y;
    }
    if(op.x>mp.x){
        px=mp.x+(opp*_strutFactor);
    }else{
        px=mp.x-(opp*_strutFactor);
    }
    if(op.y>mp.y){
        py=mp.y+(adj*_strutFactor);
    }else{
        py=mp.y-(adj*_strutFactor);
    }

    return new PointObj(px, py);
}
}

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